# AUTO MS ( MOBILE SUIT)

## Autonomous Navigation Robot

AUTO MS is designed for special application scenarios of hazardous chemicals such as flammable gas, dusty conditions, petrochemical factory, gas stations, hydrogen refueling station, ammunition depot, chemical terminal etc. It provides reliable and professional data collection and multi-function autonomous navigation robot platform.

Autonomous Navigation Robot

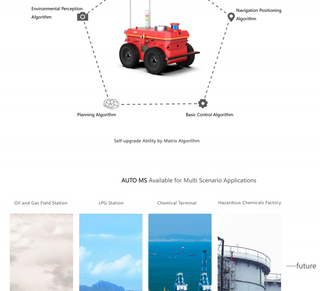
**AUTO MS ( MOBILE SUIT)** provides multiple solutions such as modular simultaneous localization and map building, autonomous navigation, path planning, autonomous obstacle avoid etc. Supporting modular carrying and multiple application expended.

Celerity Disassembly Application Modules

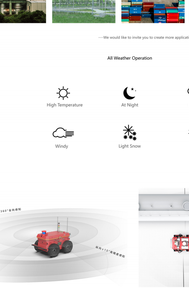


**Speaker** | **Acoustic Picker** | **Dual-Light PTZ Camera** | **Robotic Arm** | **Gas Sensor**

Modular Mounting Suit Display



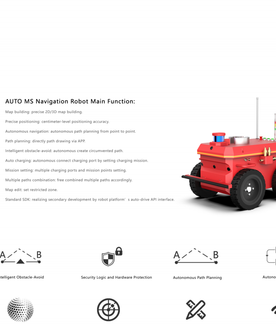
L4 Level Autonomous Navigation




Self-upgrade Ability by Matrix Algorithm

## AUTO MS Available for Multi Scenario Applications

Oil and Gas Field Station | LPG Station | Chemical Terminal | Hazardous Chemicals Factory




— We would like to invite you to create more applications together with YUHESEN.

All Weather Operation

High Temperature | At Night | Drizzle

Windy | Light Snow | Fog

Multi-sensor Integrated Obstacle-avoid Capability

Centimeter-level High-precision Mapping and Positioning Capability

Large Scale Drawing

Adapting to Indoor and Outdoor Situation

## AUTO MS Navigation Robot Main Function:

Map building: precise 2D/3D map building.

Precise positioning: centimeter-level positioning accuracy.

Autonomous navigation: autonomous path planning from point to point.

Path planning: directly path drawing via APP.

Intelligent obstacle avoid: autonomous create circumvented path.

Auto charging: autonomous connect charging port by setting charging mission.

Mission setting: multiple charging ports and mission points setting.

Multiple paths combination: free combined multiple paths accordingly.

Map edit: set restricted zone.

Standard SDK: realizing secondary development by robot platform' s auto-drive API interface.





Intelligent Obstacle Avoid | Security Logic and Hardware Protection | Autonomous Path Planning | Autonomous Charging



2D/3D Map Building | 16 Channels LiDAR | Path Drawing by APP | Multiple Sensors





1x LiDAR | 6x IPC



Explosion-proof Wireless Charging Terminal | 5x 5G Antenna

## AUTO MS Configuration:

Sensors: 16 Channels LiDAR, Ultrasonic Probe.

Communication: vehicle-grade CAN, gigabit network interactive machine.

Positioning: dual antenna RTK module, navigation module.

Computing power: NVADIA/INTEL

Platform: F8-001.

Application: AUTO MS API(Android)/Standard Secondary Development API.

## Specifications

| | | | |
|---|---|---|---|
| Product Size | 1170*1047*1000MM | Working Temperature | -20℃/60℃ |
| Weight | 270kg | Braking | Motor Brake |
| Drive form | Differential AWD | Parking | Motor Parking |
| Material | Q235 | Communication Interface | CAN 2.0B |
| Ground Clearance | 135mm | Automatic Analysis | 7 |
| Wheelbase | 580mm | Remote Control Range | 50m |
| Wheel Track | 560mm | Speed | 4.5km/h |
| Tire Outer Diameter | 400mm | Mileage | 15km |
| Motor | 1000W*4, DC Servo Motor | Working Hours | 1.45hrs |
| Battery | 36V/60AH | Climbing Capacity | 15° |
| Charging Time | 3-4h | Obstacle-Crossing Height | 80mm |
| Charging Mode | 36V/15A-30V/5A Charger | Protection Level | IP65 |





Technical Manual | ROS PACKAGE | Modular Mounting Board | High Speed CAN Interface

**When you become YUHESEN customers, we will provide you with professional and efficient technical services**

Technical experts will keep in touch with you regularly so that you can keep abreast of our product updates.

**•Open source technical support**
**•Hardware and software support**

**•Occasional return visits**
**•Technology upgrades**